

Exam 3 Spring 2008

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(1) $\odot \hat{e}_z$

$\vec{B} = B(s) \hat{e}_\phi$ (in usual cylindrical coordinates)

Ampere's law with circle of radius s :

$$\oint_{\partial S} d\vec{r} \cdot \vec{B} = \mu_0 \int_S d\vec{S} \cdot \vec{j}$$

$$d\vec{S} = s ds d\phi \hat{e}_z$$

$$\vec{j} = \begin{cases} -\frac{i}{\pi w^2} \hat{e}_z & \text{for } s < w \\ 0 & \text{for } s > w \end{cases}$$

$$d\vec{r} = s d\phi \hat{e}_\phi$$

$$\Rightarrow \oint_{\partial S} d\vec{r} \cdot \vec{B} = 2\pi s B(s) = -\frac{\mu_0 i}{\pi w^2} \begin{cases} \pi s^2 & \text{if } s < w \\ \pi w^2 & \text{if } s > w \end{cases}$$

$$\Rightarrow B(s) = -\frac{\mu_0 i}{2\pi w s} \begin{cases} s^2 & \text{for } s < w \\ w^2 & \text{for } s > w \end{cases}$$

$$B(s=w) = -\frac{\mu_0 i}{2\pi w}$$

Assume $x > 0$. Then $\phi = 0$ and $x = s$

(a) $0 < x < w$

$$\frac{\cancel{\mu_0 i} x}{2\pi w} = \frac{1}{2} \frac{\cancel{\mu_0 i} x}{\cancel{\pi w} x} \Rightarrow x = \frac{w}{2} < w \Rightarrow \text{solution}$$

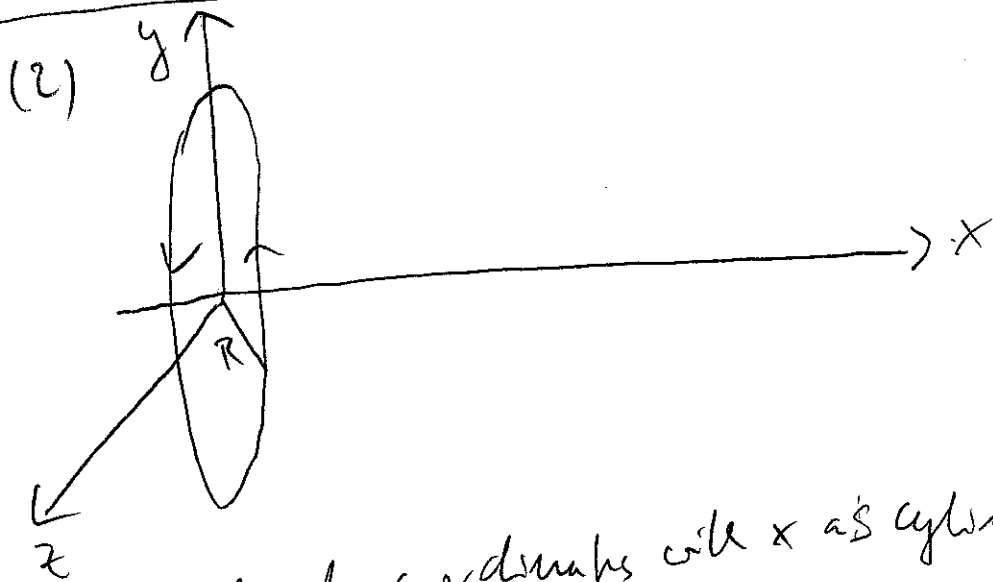
(b) $x > w$

$$\frac{\cancel{\mu_0 i}}{2\pi x} = \frac{1}{2} \frac{\cancel{\mu_0 i}}{\cancel{\pi w}} \Rightarrow x = 2w > w \Rightarrow \text{solution}$$

Some the magnitude
 $|\vec{B}| = \frac{\mu_0 i}{2\pi w^2 s} \begin{cases} s^2 & \text{for } s < w \\ w^2 & \text{for } s > w \end{cases}$

is independent of ϕ . The other solutions on the x axis
 are at $\phi = \pi$ i.e.

$$x = -\frac{w}{2} \text{ and } x = -2w$$



(a) Use cylinder coordinates with x as cylinder axis

Then we set

$$C: \vec{r}^1(\phi) = R \vec{i}_\phi(\phi) \Rightarrow d\vec{r}^1 = R \vec{i}_\phi(\phi) d\phi$$

$$\vec{r}^2 = x \vec{i}_x$$

on Biot-Savart's law:

$$\vec{B}(\vec{r}^2) = \frac{\mu_0 i}{4\pi} \int_C d\vec{r}^1 \times \frac{\vec{r}^2 - \vec{r}^1}{|\vec{r}^2 - \vec{r}^1|^2}$$

$$\vec{r}^2 - \vec{r}^1 = x \vec{i}_x - R \vec{i}_\phi \Rightarrow d\vec{r}^1 \times (\vec{r}^2 - \vec{r}^1) = d\vec{r}^1 \times (x \vec{i}_x - R \vec{i}_\phi)$$

$$|\vec{r}^2 - \vec{r}^1| = \sqrt{x^2 + R^2}$$

$$= R d\phi [x \vec{i}_\phi(\phi) + R \vec{i}_x]$$

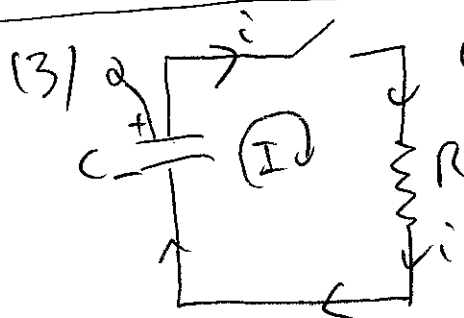
Since $\int d\phi \vec{i}_\phi(\phi) = 0$

$$\vec{B}(\vec{x}) = \frac{\mu_0 i}{4\pi} \int_0^{2\pi} d\varphi \frac{R^2 \vec{i}_x}{(R^2 + x^2)^{3/2}}$$

(3)

$$\vec{B}(\vec{x}) = \frac{\mu_0 i R^2}{2} \frac{\vec{i}_x}{(R^2 + x^2)^{3/2}}$$

$$(b) \vec{F} = q \vec{v} \times \vec{B}(\vec{x}) = 0$$



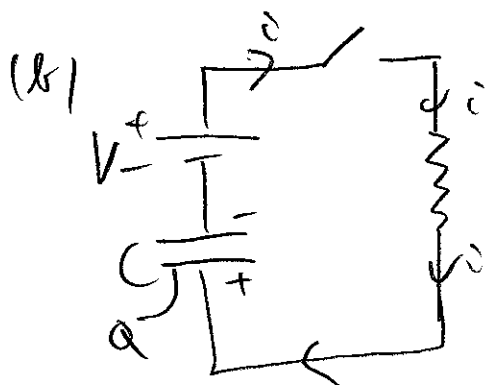
(a) Faraday's Law

$$\oint_C d\vec{r} \cdot \vec{E} = 0 \quad (L=0)$$

$$-\frac{Q}{C} + Ri = 0$$

$$i = -\dot{Q} \Rightarrow \dot{Q} = -\frac{Q}{RC} \Rightarrow$$

$$Q(t) = Q_0 \exp\left(-\frac{t}{RC}\right)$$



$$Q(0) = 0$$

$$-V + \frac{Q}{C} + Ri = 0$$

$$\Rightarrow i + \frac{Q}{RC} = \frac{V}{R}$$

$$i = +\dot{Q}$$

$$\Rightarrow \dot{Q} + \frac{Q}{RC} = \frac{V}{R}$$

Homogeneous equation has general solution given above

$$Q_{hom} = A \exp\left(-\frac{t}{RC}\right) \text{ with } A = \text{const.}$$

Particular solution of inhom. q .

(9)

$$Q = Q_1 = \text{const} \Rightarrow \frac{A_1}{RC} = \frac{V}{R} \Rightarrow A_1 = CV$$

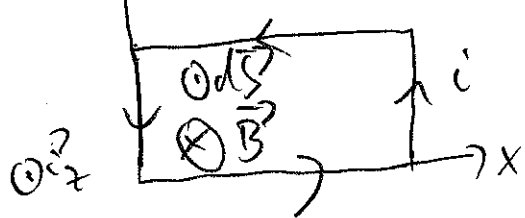
$$Q(t) = CV + A \exp\left(-\frac{t}{RC}\right)$$

$$Q(t) = CV + A \stackrel{!}{=} 0 \Rightarrow A = -CV$$

$$\Rightarrow Q(t) = CV \left[1 - \exp\left(-\frac{t}{RC}\right) \right]$$

(9) $R = \frac{Z(\omega + i)}{A}$

$$\vec{B} = -B(t) \vec{e}_z$$



Faraday's law

$$\oint_{\partial S} d\vec{r} \cdot \vec{E} = Ri = -\frac{d}{dt} (\text{HW } B)$$

$$\Rightarrow i = \frac{HW}{R} \dot{B} = \frac{HW(A\omega + i)}{Z(\omega + i)} (24t^3 + 7)$$