

Exercises

Exercise 1: Matrix groups

So-called matrix groups play an important role in mathematics and physics. Therefore, some of these groups will be investigated in more detail in this exercise.

- (a) The set of regular (means non-vanishing determinant) real-valued ($N \times N$) matrices is denoted as $GL(N, \mathbb{R})$. Show that this set together with the standard matrix multiplication forms a group.
- (b) The set of unimodular (means determinant equal 1) real-valued ($N \times N$) matrices is denoted as $SL(N, \mathbb{R})$. Show that this set together with the standard matrix multiplication forms a group. Show in addition that it is a subgroup of $GL(N, \mathbb{R})$.
- (c) We define the following ($2N \times 2N$) matrix

$$J = \begin{pmatrix} 0_{N \times N} & \mathbb{1}_{N \times N} \\ -\mathbb{1}_{N \times N} & 0_{N \times N} \end{pmatrix},$$

where $0_{N \times N}$ denotes the N -dimensional null matrix and $\mathbb{1}_{N \times N}$ the N -dimensional unit matrix. The $2N \times 2N$ matrices M with the property

$$M^T J M = J,$$

form the set of all real-valued symplectic ($2N \times 2N$) matrices, denoted as $Sp(2N, \mathbb{R})$. Show that the above relation implies $\det(M) = \pm 1$. Then show that $Sp(2N, \mathbb{R})$ together with the standard matrix multiplication forms a group. Is $Sp(2N, \mathbb{R})$ a subgroup of $GL(2N, \mathbb{R})$?

Exercise 2: The groups $U(N)$ and $SU(N)$

The Lie groups $U(N)$ and $SU(N)$ are very important for physics. Here, $U(N)$ denotes the group of unitary ($N \times N$) matrices and $SU(N)$ the group of unitary ($N \times N$) matrices with determinant 1. It is intuitively clear that $SU(N)$ is a Lie subgroup of $U(N)$. The exact relation between both Lie groups is

$$U(N) = SU(N) \times U(1)$$

so that each $g \in U(N)$ can be written as

$$D(g) = D(h) \exp\left(-\frac{i}{\hbar} \alpha_0 \hat{T}_0\right),$$

where $\hat{T}_0 \propto \mathbb{1}_{N \times N}$ and $h \in SU(N)$. Here, $D(g)$ and $D(h)$ are ($N \times N$) matrix representations of elements $g \in U(N)$ and $h \in SU(N)$, respectively. The exponential in the above equation is an ($N \times N$) matrix representation of an element of $U(1)$.

Since $U(N)$ is a Lie group, its elements can be also written as

$$\hat{U}(\alpha_0, \alpha_1, \dots, \alpha_{n(N)}) = \exp\left(-\frac{i}{\hbar} \sum_{a=0}^{n(N)} \alpha_a \hat{T}_a\right),$$

where \hat{T}_a , $a = 1, \dots, n(N)$ denote the generators of $SU(N)$ and $\hat{T}_0 \propto \mathbb{1}_{N \times N}$ is the additional generator of $U(1)$.

The Lie algebra of $SU(N)$ is given by

$$[\hat{T}_a, \hat{T}_b] = i\hbar \sum_{c=1}^{n(N)} f_{abc} \hat{T}_c,$$

where the structure constants f_{abc} are completely antisymmetric in a basis where $\text{Tr}(\hat{T}_a \hat{T}_b) \propto \delta_{ab}$. The anti-commutator of two $SU(N)$ generators is given by

$$\{\hat{T}_a, \hat{T}_b\} = \frac{\hbar^2}{N} \delta_{ab} \mathbb{1}_{N \times N} + \hbar \sum_{c=1}^{n(N)} d_{abc} \hat{T}_c.$$

Here, d_{abc} are the completely symmetric structure constants of $SU(N)$.

(i) Determine the number $n(N)$ of generators of $SU(N)$ as function of N .

(ii) Determine \hat{T}_0 such that the orthogonality relation $\text{Tr}(\hat{T}_a \hat{T}_b) = \frac{\hbar^2}{2} \delta_{ab}$, $a, b = 0, 1, \dots, n(N)$ is fulfilled.

(iii) Show that

$$f_{abc} = \frac{2}{i\hbar^3} \text{Tr} \left\{ [\hat{T}_a, \hat{T}_b] \hat{T}_c \right\}, \quad d_{abc} = \frac{2}{\hbar^3} \text{Tr} \left(\left\{ \hat{T}_a, \hat{T}_b \right\} \hat{T}_c \right).$$

(iv) Prove the Jacobi identity

$$\sum_{n=1}^{n(N)} (f_{abn} d_{ncd} + f_{dbn} d_{nca} + f_{cbn} d_{nad}) = 0.$$

(v) Show that

$$\hat{C}_1 = \sum_{a,b,c=1}^{n(N)} f_{abc} \hat{T}_a \hat{T}_b \hat{T}_c, \quad \hat{C}_2 = \sum_{a,b,c=1}^{n(N)} d_{abc} \hat{T}_a \hat{T}_b \hat{T}_c$$

are Casimir operators of the Lie group $SU(N)$ and compute \hat{C}_1 explicitly for $SU(2)$.

(vi) Generalize the above commutation and anti-commutation relations to the generators of $U(N)$ and determine the additional structure constants f_{abc} and d_{abc} .